# MTi-630R

- Rugged, IP68-rated AHRS
- 0.2 deg roll/pitch, 1 deg heading accuracy
- Full Graphical User Interface (GUI) and Software Development Kit (SDK) available

The MTi-630R is an Attitude Heading and Reference System (AHRS) with a rugged housing, featuring IP68 protection against environmental influences. It is designed for easy integration and seamless interfacing with other equipment. As a part of the MTi-600-series, this module is lightweight, robust, cost-effective and easy to integrate. It is also highly flexible, with native CAN support.

The MTi-630R is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms.



- White label and OEM integration options available
- 3D models available on request
- Available online via Digi-Key, Mouser, Farnell and local distributors

#### **Sensor Fusion Performance**

Roll, Pitch		0,2 deg RMS	
Yaw/Heading —		1 deg RMS	
Strapdown Inte	gration (SDI) ———	Yes	
Gyroscope			
Standard full ra	nge ————	2000 deg/s	
In-run bias stab	oility ———	8 deg/h	
Bandwidth (-3d	В)	520 Hz	
Noise Density		0.007 °/s/√Hz	
g-sensitivity (ca	alibr.)	0.001 °/s/g	
Accelerome	eter		
Standard full ra	nge ————	10 g	

Standard rail railige	10 9
In-run bias stability	10 (x,y) 15(z) μg
Bandwidth (-3dB)	500 Hz
Noise Density	60 μg/√Hz

### Magnetometer

Standard full range	+/- 8 G
Total RMS noise	1 mG
Non-linearity	0.2%
Resolution	0.25 mG

#### **GNSS Receiver**

Brand ————————————————————————————————————	n/a
Model	n/a
RTCM input port	n/a

#### **Barometer**

Standard full range	300-1250 hPa
Total RMS noise	1.2 Pa
Relative accuracy	+/- 8 Pa (~0.5m)

#### **Mechanical**

IP68
-40 to 85 °C
Aluminum
No restriction, full 360° in all axes
56.50x40.90x24.75 mm
Main: ODU (AMC HD 12 pins)
75 g

## **Electrical**

Input voltage	4.5 to 24V
Power consumption (typ)	<1 W

#### Interfaces / IO

Interfaces	CAN, RS232
Sync Options	SyncIn, SyncOut, ClockSync
Protocols	Xbus, ASCII (NMEA) or CAN
Clock drift	10 ppm (or external)
Output Frequency	2 kHz, 400 Hz SDI
Built-in-self test	Yes

#### **Software Suite**

GUI (Windows/Linux)	MT Manager Firmware updater,
	Magnetic Field Mapper
SDK (Example code)	C++, C#, python, Matlab, Nucleo,
	public source code
Drivers	LabVIEW, ROS, GO
Support	BASE by XSENS: online manuals,
	community and knowledge base



